

# SPECIFICATION

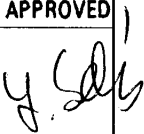
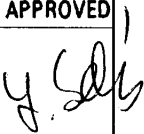
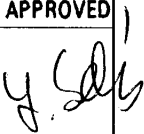
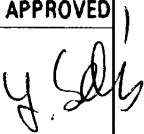
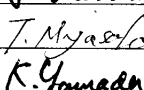
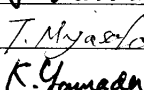
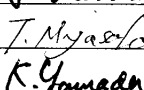
Device Name : IGBT - IPM

Type Name : 7MBP75TEA120

Spec. No. : MS6M00747

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Fuji Electric Co., Ltd.  
Matsumoto Factory

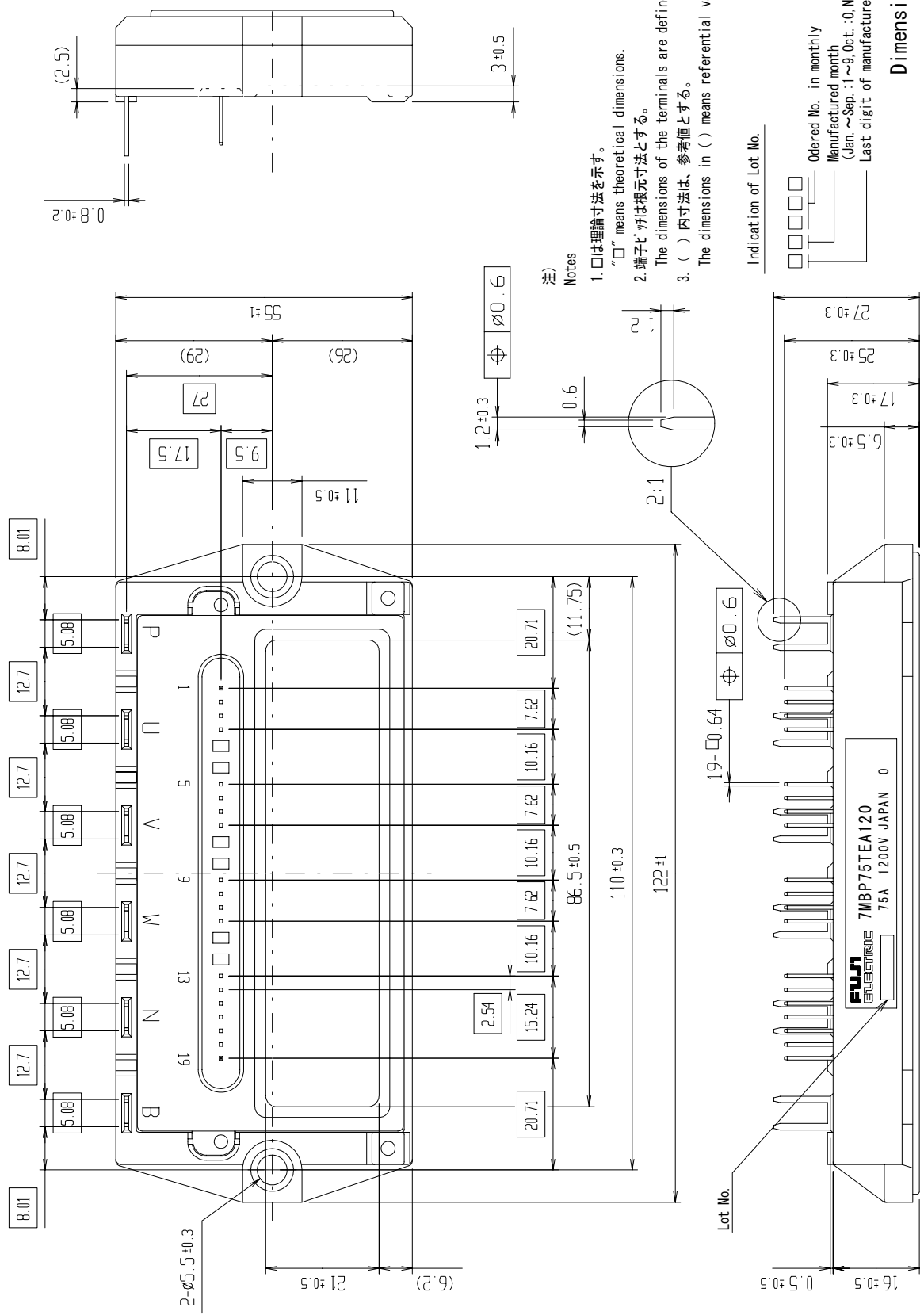
	DATE	NAME	APPROVED	<b>Fuji Electric Co., Ltd.</b>					
DRAWN	Oct - 3 - '03	Y. Kusunoki							
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				DWG. NO.	MS6M00747	1 / 23			



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# 1. Package Outline Drawings (a)

Package type : P622



注) Notes  
 1. □は理論寸法を示す。  
 "□" means theoretical dimensions.  
 2. 端子"φ"は根寸法とする。  
 The dimensions of the terminals are defined at the bottom.  
 3. ( ) 内寸法は、参考値とする。  
 The dimensions in ( ) means referential values.

Indication of Lot No.

Ordered No. in monthly  
 Manufactured month  
 (Jan. ~ Sep. : 1~9, Oct. : 0, Nov. : N, Dec. : D)  
 Last digit of manufactured year

Dimensions in mm

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## 2. Pin Descriptions

### Main circuit

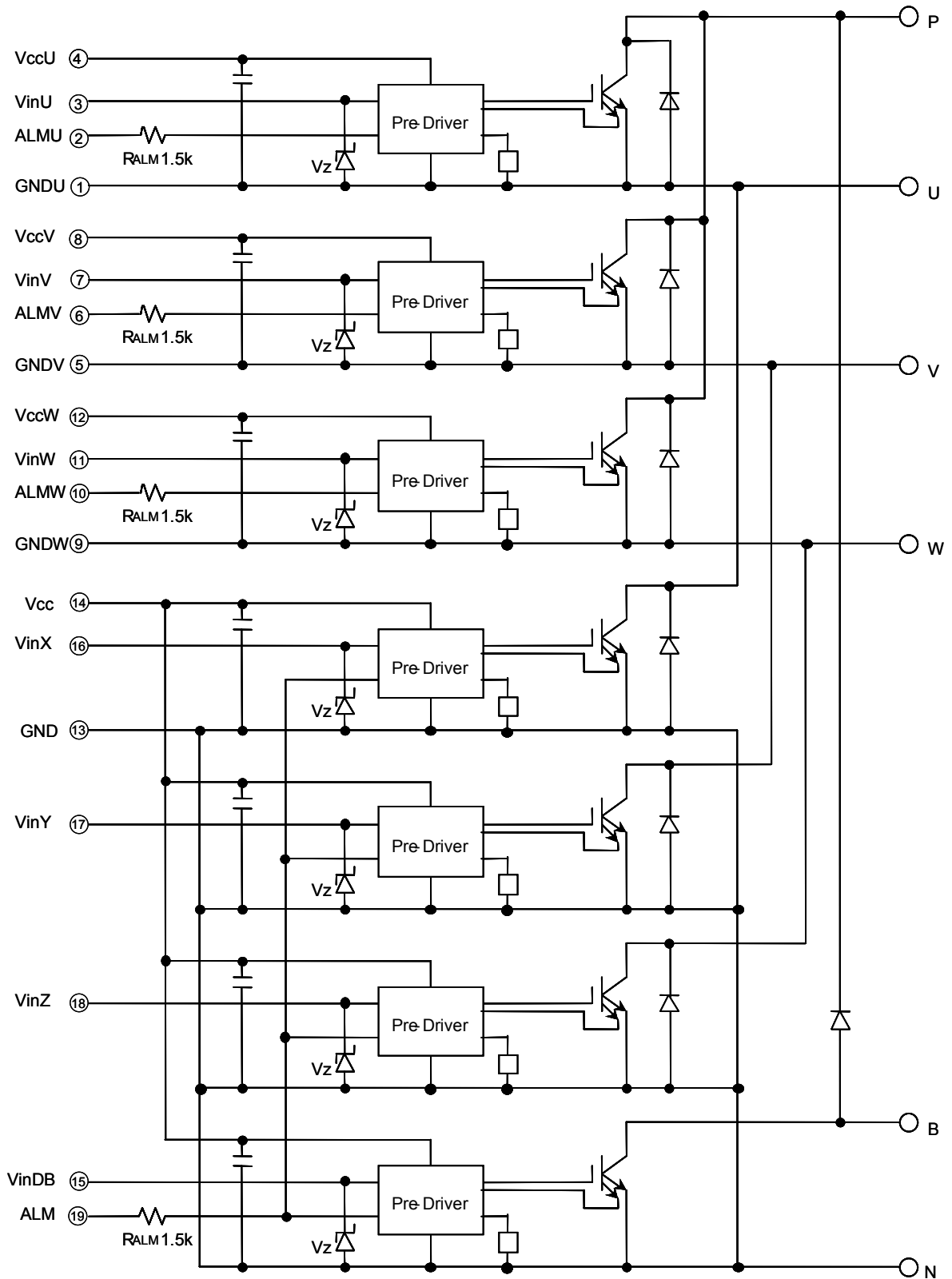
Symbol	Description
P	Positive input supply voltage.
U	Output (U).
V	Output (V).
W	Output (W).
N	Negative input supply voltage.
B	Collector terminal of Brake IGBT.

### Control circuit

No.	Symbol	Description
①	GNDU	High side ground (U).
②	ALMU	Alarm signal output (U).
③	VinU	Logic input for IGBT gate drive (U).
④	VccU	High side supply voltage (U).
⑤	GNDV	High side ground (V).
⑥	ALMV	Alarm signal output (V).
⑦	VinV	Logic input for IGBT gate drive (V).
⑧	VccV	High side supply voltage (V).
⑨	GNDW	High side ground (W).
⑩	ALMW	Alarm signal output (W).
⑪	VinW	Logic input for IGBT gate drive (W).
⑫	VccW	High side supply voltage (W).
⑬	GND	Low side ground.
⑭	Vcc	Low side supply voltage.
⑮	VinDB	Logic input for Brake IGBT gate drive.
⑯	VinX	Logic input for IGBT gate drive (X).
⑰	VinY	Logic input for IGBT gate drive (Y).
⑱	VinZ	Logic input for IGBT gate drive (Z).
⑲	ALM	Low side alarm signal output.

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### 3. Block Diagram



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Pre-drivers include following functions

1. Amplifier for driver
2. Short circuit protection
3. Under voltage lockout circuit
4. Over current protection
5. IGBT chip over heating protection

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H04-004-03

#### 4. Absolute Maximum Ratings

Tc=25°C unless otherwise specified.

Items		Symbol	Min.	Max.	Units	
Bus Voltage (between terminal P and N)	DC	V <sub>DC</sub>	0	900	V	
	Surge	V <sub>DC(surge)</sub>	0	1000	V	
	Short operating	V <sub>sc</sub>	400	800	V	
Collector-Emitter Voltage *1		V <sub>ces</sub>	0	1200	V	
Inverter	Collector Current	DC	I <sub>c</sub>	-	75	A
		1ms	I <sub>cp</sub>	-	150	A
		Duty=100% *2	-I <sub>c</sub>	-	75	A
	Collector Power Dissipation	One transistor *3	P <sub>c</sub>	-	368	W
Brake	Collector Current	DC	I <sub>c</sub>	-	25	A
		1ms	I <sub>cp</sub>	-	50	A
	Forward Current Diode		I <sub>F</sub>	-	25	A
	Collector Power Dissipation	One transistor *3	P <sub>c</sub>	-	212	W
Supply Voltage of Pre-Driver *4		V <sub>cc</sub>	-0.5	20	V	
Input Signal Voltage *5		V <sub>in</sub>	-0.5	V <sub>cc</sub> +0.5	V	
Input Signal Current		I <sub>in</sub>	-	3	mA	
Alarm Signal Voltage *6		VALM	-0.5	V <sub>cc</sub>	V	
Alarm Signal Current *7		I <sub>ALM</sub>	-	20	mA	
Junction Temperature		T <sub>j</sub>	-	150	°C	
Operating Case Temperature		T <sub>opr</sub>	-20	100	°C	
Storage Temperature		T <sub>stg</sub>	-40	125	°C	
Solder Temperature *8		T <sub>sol</sub>	-	260		
Isolating Voltage (Terminal to base, 50/60Hz sine wave 1min.)		V <sub>iso</sub>	-	AC2500	V	
Screw Torque	Mounting (M5)	-	-	3.5	Nm	

#### Note

- \*1 : V<sub>ces</sub> shall be applied to the input voltage between terminal P and U or V or W or DB, N and U or V or W or DB.
- \*2 :  $125^{\circ}\text{C}/\text{FWD } R_{th(j-c)} / (I_c \times V_F \text{ MAX}) = 125/0.61 / (75 \times 2.0) \times 100 = 100\%$
- \*3 : P<sub>c</sub>=125°C/IGBT R<sub>th(j-c)</sub>=125/0.34=368W [Inverter]  
P<sub>c</sub>=125°C/IGBT R<sub>th(j-c)</sub>=125/0.59=212W [Brake]
- \*4 : V<sub>CC</sub> shall be applied to the input voltage between terminal No.4 and 1, 8 and 5, 12 and 9, 14 and 13
- \*5 : V<sub>in</sub> shall be applied to the input voltage between terminal No.3 and 1, 7 and 5, 11 and 9, 16,17,18 and 13.
- \*6 : VALM shall be applied to the voltage between terminal No.2 and 1, No6 and 5, No10 and 9, No.19 and 13.
- \*7 : I<sub>ALM</sub> shall be applied to the input current to terminal No.2,6,10 and 19.
- \*8 : Immersion time 10±1sec.

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5. Electrical Characteristics

T<sub>j</sub>=25°C, V<sub>cc</sub>=15V unless otherwise specified.

5.1 Main circuit

Item		Symbol	Conditions	Min.	Typ.	Max.	Units
Inverter	Collector Current at off signal input	I <sub>CEs</sub>	V <sub>CE</sub> =1200V V <sub>in</sub> terminal open.	-	-	1.0	mA
	Collector-Emitter saturation voltage	V <sub>CE(sat)</sub>	I <sub>c</sub> =75A Terminal	-	-	3.1	V
			Chip	-	2.2	-	V
Forward voltage of FWD	V <sub>F</sub>	-I <sub>c</sub> =75A Terminal	Chip	-	1.6	-	V
			Chip	-	1.6	-	V
Brake	Collector Current at off signal input	I <sub>CEs</sub>	V <sub>CE</sub> =1200V V <sub>in</sub> terminal open.	-	-	1.0	mA
	Collector-Emitter saturation voltage	V <sub>CE(sat)</sub>	I <sub>c</sub> =25A Terminal	-	-	2.6	V
			Chip	-	1.9	-	V
Forward voltage of Diode	V <sub>F</sub>	-I <sub>c</sub> =25A Terminal	Chip	-	2.3	-	V
			Chip	-	2.3	-	V
Turn-on time		ton	V <sub>DC</sub> =600V, T <sub>j</sub> =125°C	1.2	-	-	us
Turn-off time		toff	I <sub>c</sub> =75A Fig.1, Fig.6	-	-	3.6	
Reverse recovery time		trr	V <sub>DC</sub> =600V I <sub>F</sub> =75A Fig.1, Fig.6	-	-	0.3	

5.2 Control circuit

Item		Symbol	Conditions	Min.	Typ.	Max.	Units
Supply current of P-side pre-driver (one unit)		I <sub>ccp</sub>	Switching Frequency : 0~15kHz	-	-	15	mA
Supply current of N-side pre-driver		I <sub>ccn</sub>	T <sub>c</sub> =-20~125°C Fig.7	-	-	45	mA
Input signal threshold voltage	V <sub>in(th)</sub>	ON		1.00	1.35	1.70	V
		OFF		1.25	1.60	1.95	
Input Zener Voltage		V <sub>z</sub>	R <sub>in</sub> =20kΩ	-	8.0	-	V
Alarm Signal Hold Time	t <sub>ALM</sub>	T <sub>c</sub> =-20°C Fig.2		1.1	-	-	ms
		T <sub>c</sub> =25°C Fig.2		-	2.0	-	
		T <sub>c</sub> =125°C Fig.2		-	-	4.0	
Current Limit Resistor		R <sub>ALM</sub>	Alarm terminal	1425	1500	1575	Ω

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### 5.3 Protection Section (Vcc=15V)

Item	Symbol	Conditions	Min.	Typ.	Max.	Units
Over Current Protection Level of Inverter circuit	loc	Tj=125°C	113	-	-	A
Over Current Protection Level of Brake circuit		Tj=125°C	38	-	-	A
Over Current Protection Delay time	tdoc	Tj=125°C	-	5	-	us
SC Protection Delay time	tsc	Tj=125°C Fig.4	-	-	8	us
IGBT Chips Over Heating Protection Temperature Level	TjOH	Surface of IGBT Chips	150	-	-	°C
Over Heating Protection Hysteresis	TjH		-	20	-	°C
Under Voltage Protection Level	VUV		11.0	-	12.5	V
Under Voltage Protection Hysteresis	VH		0.2	0.5	-	

### 6. Thermal Characteristics (Tc=25°C)

Item		Symbol	Min.	Typ.	Max.	Units	
Junction to Case Thermal Resistance *9	Inverter	IGBT	Rth(j-c)	-	-	0.34	°C/W
		FWD	Rth(j-c)	-	-	0.61	
	Brake	IGBT	Rth(j-c)	-	-	0.59	
Case to Fin Thermal Resistance with Compound			Rth(c-f)	-	0.05	-	

\*9: Rth(j-c) shall be specified to the thermal resistance between chip and copper base surface under the chip.

### 7. Noise Immunity (Vdc=300V, Vcc=15V, Test Circuit Fig 5.)

Item	Conditions	Min.	Typ.	Max.	Units
Common mode rectangular noise	Pulse width 1us, polarity ±, 10 minuts Judge : no over-current, no miss operating	±2.0	-	-	kV
Common mode lightning surge	Rise time 1.2us, Fall time 50us Interval 20s, 10 times Judge : no over-current, no miss operating	±5.0	-	-	kV

### 8. Recommended Operating Conditions

Item	Symbol	Min.	Typ.	Max.	Units
DC Bus Voltage	VDC	-	-	800	V
Power Supply Voltage of Pre-Driver	Vcc	13.5	15.0	16.5	V
Screw Torque (M5)	-	2.5	-	3.0	Nm

### 9. Weight

Item	Symbol	Min.	Typ.	Max.	Units
Weight	Wt	-	270	-	g

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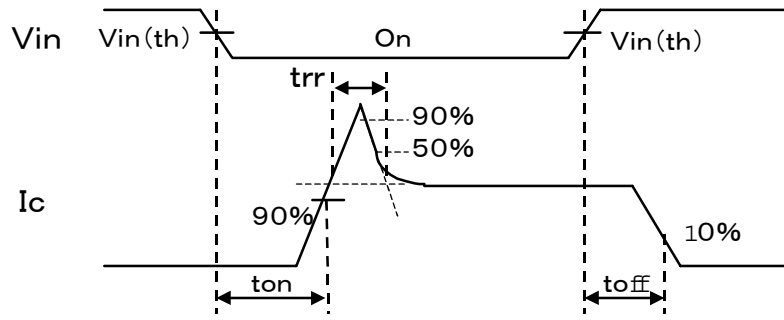


Figure 1. Switching Time Waveform Definitions

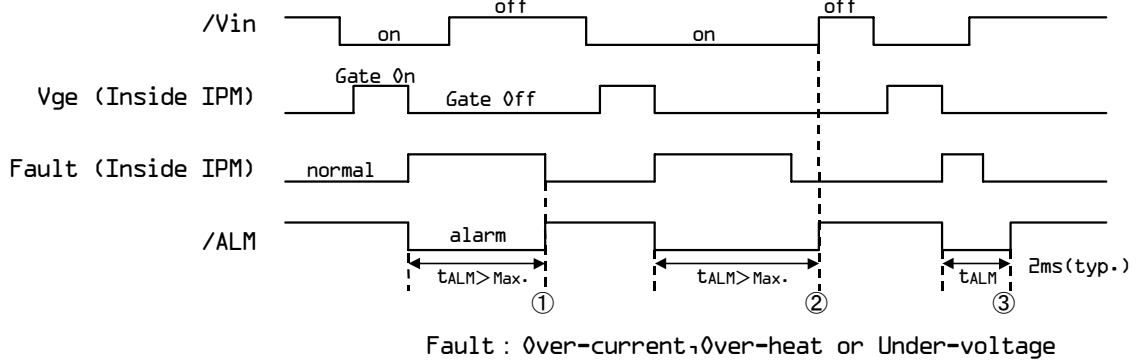


Figure 2. Input/Output Timing Diagram

Necessary conditions for alarm reset (refer to ① to ③ in figure2.)

- ① This represents the case when a failure-causing Fault lasts for a period more than  $t_{ALM}$ .  
The alarm resets when the input  $V_{in}$  is OFF and the Fault has disappeared.
- ② This represents the case when the ON condition of the input  $V_{in}$  lasts for a period more than  $t_{ALM}$ . The alarm resets when the  $V_{in}$  turns OFF under no Fault conditions.
- ③ This represents the case when the Fault disappears and the  $V_{in}$  turns OFF within  $t_{ALM}$ .  
The alarm resets after lasting for a period of the specified time  $t_{ALM}$ .

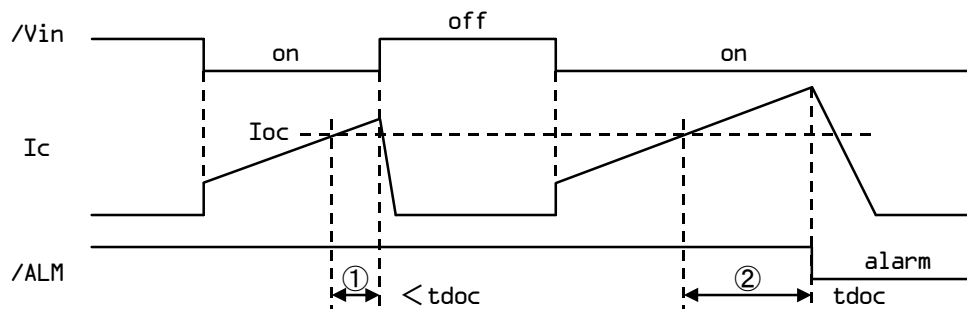


Figure 3. Over-current Protection Timing Diagram

- Period ①: When a collector current over the OC level flows and the OFF command is input within a period less than the trip delay time  $t_{doc}$ , the current is hard-interrupted and no alarm is output.
- Period ②: When a collector current over the OC level flows for a period more than the trip delay time  $t_{doc}$ , the current is soft-interrupted. If this is detected at the lower arm IGBTs, an alarm is output.

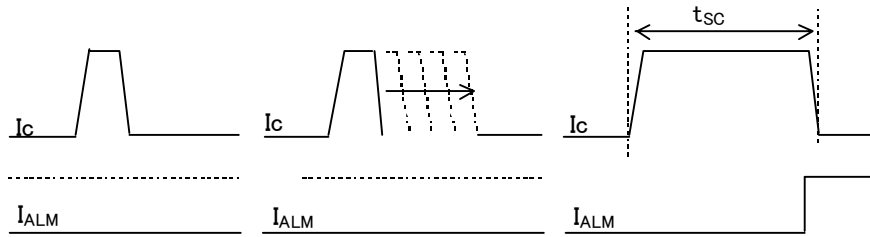


Figure.4 Definition of tsc

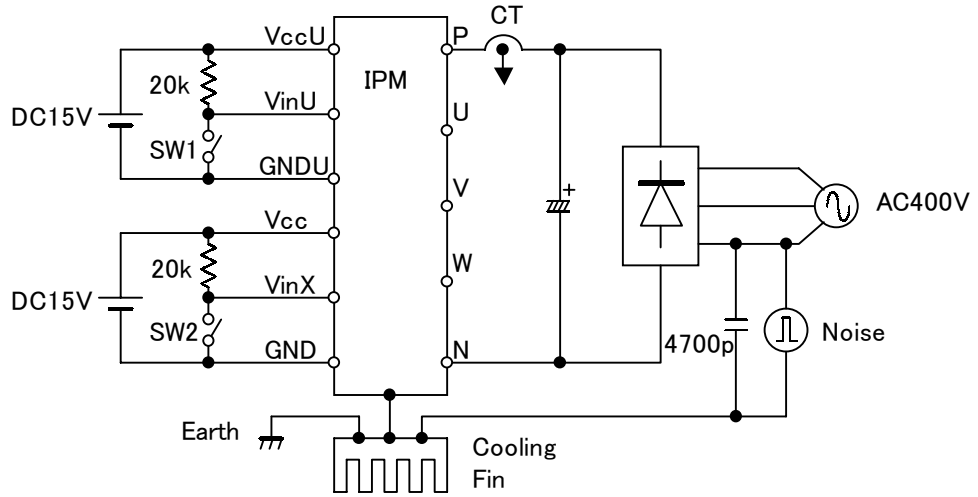


Figure 5. Noise Test Circuit

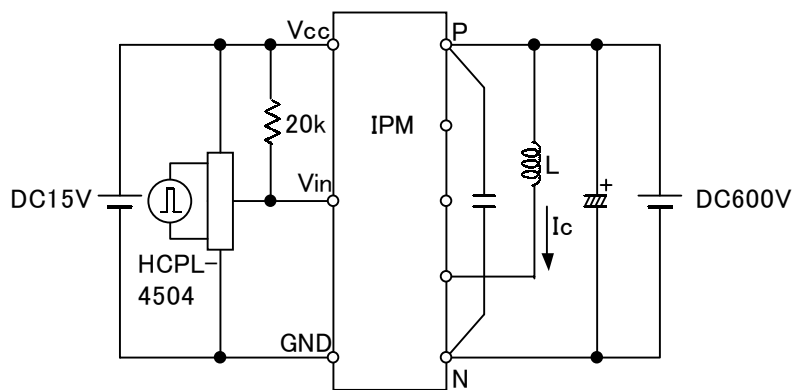


Figure 6. Switching Characteristics Test Circuit

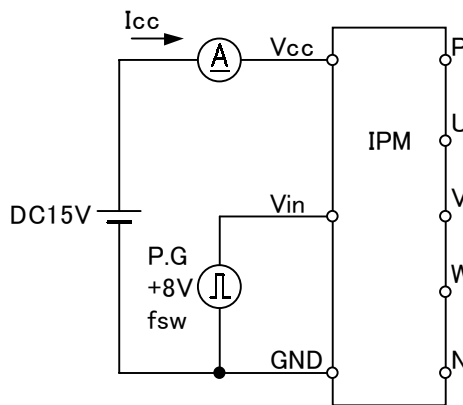


Figure 7. Icc Test Circuit

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## 10. Truth table

### 10.1 IGBT Control

The following table shows the IGBT ON/OFF status with respect to the input signal Vin.

The IGBT turn-on when Vin is at "Low" level under no alarm condition.

Input (Vin)	Output (IGBT)
Low	ON
High	OFF

### 10.2 Fault Detection

- (1) When a fault is detected at the high side, only the detected arm stops its output.

At that time the IPM doesn't any alarm.

- (2) When a fault is detected at the low side, all the lower arms stop their outputs and the IPM outputs an alarm of the low side.

	Fault	IGBT				Alarm Output			
		U-phase	V-phase	W-phase	Low side	ALM-U	ALM-V	ALM-W	ALM
High side U-phase	OC	OFF	*	*	*	L	H	H	H
	UV	OFF	*	*	*	L	H	H	H
	TjOH	OFF	*	*	*	L	H	H	H
High side V-phase	OC	*	OFF	*	*	H	L	H	H
	UV	*	OFF	*	*	H	L	H	H
	TjOH	*	OFF	*	*	H	L	H	H
High side W-phase	OC	*	*	OFF	*	H	H	L	H
	UV	*	*	OFF	*	H	H	L	H
	TjOH	*	*	OFF	*	H	H	L	H
Low side	OC	*	*	*	OFF	H	H	H	L
	UV	*	*	*	OFF	H	H	H	L
	TjOH	*	*	*	OFF	H	H	H	L

\*: Depend on input logic.

## 11. Cautions for design and application 設計・適用上の注意点

1. Trace routing layout should be designed with particular attention to least stray capacity between the primary and secondary sides of optical isolators by minimizing the wiring length between the optical isolators and the IPM input terminals as possible.  
 フォトカプラとIPMの入力端子間の配線は極力短くし、フォトカプラの一次側と二次側の浮遊容量を小さくしたパターンレイアウトにしてください。
2. Mount a capacitor between Vcc and GND of each high-speed optical isolator as close to as possible.  
 高速フォトカプラのVcc-GND間に、コンデンサを出来るだけ近接して取り付けて下さい。
3. For the high-speed optical isolator, use high-CMR type one with  $t_{pHL}$ ,  $t_{pLH} \leq 0.8\mu s$ .  
 高速フォトカプラは、 $t_{pHL}, t_{pLH} \leq 0.8\mu s$ 、高CMRタイプをご使用ください。
4. For the alarm output circuit, use low-speed type optical isolators with  $CTR \geq 100\%$ .  
 アラーム出力回路は、低速フォトカプラ $CTR \geq 100\%$ のタイプをご使用ください。
5. For the control power Vcc, use four power supplies isolated each. And they should be designed to reduce the voltage variations.  
 制御電源Vccは、絶縁された4電源を使用してください。また、電圧変動を抑えた設計として下さい。
6. Suppress surge voltages as possible by reducing the inductance between the DC bus P and N, and connecting some capacitors between the P and N terminals.  
 P-N間の直流母線は出来るだけ低インダクタンス化し、P-N端子間にコンデンサを接続するなどしてサージ電圧を低減して下さい。
7. To prevent noise intrusion from the AC lines, connect a capacitor of some 4700pF between the three-phase lines each and the ground.  
 ACラインからのノイズ侵入を防ぐために、3相各線-アース間に4700pF程のコンデンサを接続して下さい。
8. At the external circuit, never connect the control terminal GNDU to the main terminal U-phase, GNDV to V-phase, GNDW to W-phase, and GND to N-phase. Otherwise, malfunctions may be caused.  
 制御端子GNDUと主端子U相、制御端子GNDVと主端子V相、制御端子GNDWと主端子W相、制御端子GNDと主端子Nを外部回路で接続しないで下さい。誤動作の原因になります。
9. Take note that an optical isolator's response to the primary input signal becomes slow if a capacitor is connected between the input terminal and GND.  
 入力端子-GND間にコンデンサを接続すると、フォトカプラ一次側入力信号に対する応答時間が長くなりますのでご注意ください。
10. Taking the used isolator's CTR into account, design with a sufficient allowance to decide the primary forward current of the optical isolator.  
 フォトカプラの一次側電流は、お使いのフォトカプラのCTRを考慮し十分に余裕をもった設計にしてください。

11. In case of mounting this product on cooling fin, use thermal compound to secure thermal conductivity. If the thermal compound amount was not enough or its applying method was not suitable, its spreading will not be enough, then, thermal conductivity will be worse and thermal run away destruction may occur.

Confirm spreading state of the thermal compound when its applying to this product.

(Spreading state of the thermal compound can be confirmed by removing this product after mounting.)

素子を冷却フィンに取り付ける際には、熱伝導を確保するためのコンパウンド等をご使用ください。

又、塗布量が不足したり、塗布方法が不適だったりすると、コンパウンドが十分に素子全体に広がらず、

放熱悪化による熱暴走破壊に繋がる事があります。コンパウンドを塗布する際には、

製品全面にコンパウンドが広がっている事を確認してください。

(実装した後に素子を取りはずすとコンパウンドの広がり具合を確認する事が出来ます。)

12. Use this product with keeping the cooling fin's flatness between screw holes within 100um at 100mm and the roughness within 10um. Also keep the tightening torque within the limits of this specification. Too large convex of cooling fin may cause isolation breakdown and this may lead to a critical accident. On the other hand, too large concave of cooling fin makes gap between this product and the fin bigger, then, thermal conductivity will be worse and over heat destruction may occur.

冷却フィンがネジ取り付け位置間で平坦度を100mmで

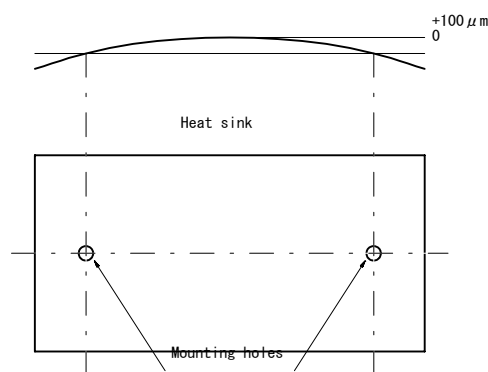
100um以下、表面の粗さは10um以下にしてください。

過大な凸反りがあつたりすると本製品が絶縁破壊を起こし、重大事故に発展する場合があります。

また、過大な凹反りやゆがみ等があると、本製品と

冷却フィンに間に空隙が生じて放熱が悪くなり、

熱破壊に繋がる場合があります。



13. This product is designed on the assumption that it applies to an inverter use. Sufficient examination is required when applying to a converter use. Please contact Fuji Electric Co.,Ltd if you would like to applying to converter use.

本製品は、インバータ用途への適用を前提に設計されております。コンバータ用途へ適用される場合は、

十分な検討が必要です。もし、コンバータへ適用される場合は御連絡ください。

14. Please see the 『Fuji IGBT-IPM R SERIES APPLICATION MANUAL』 and 『Fuji IGBT MODULES N-SERIES APPLICATION MANUAL』.

『富士IGBT-IPM Rシリーズ アプリケーションマニュアル』及び『IGBTモジュール Nシリーズ アプリケーションマニュアル』を御参照ください。

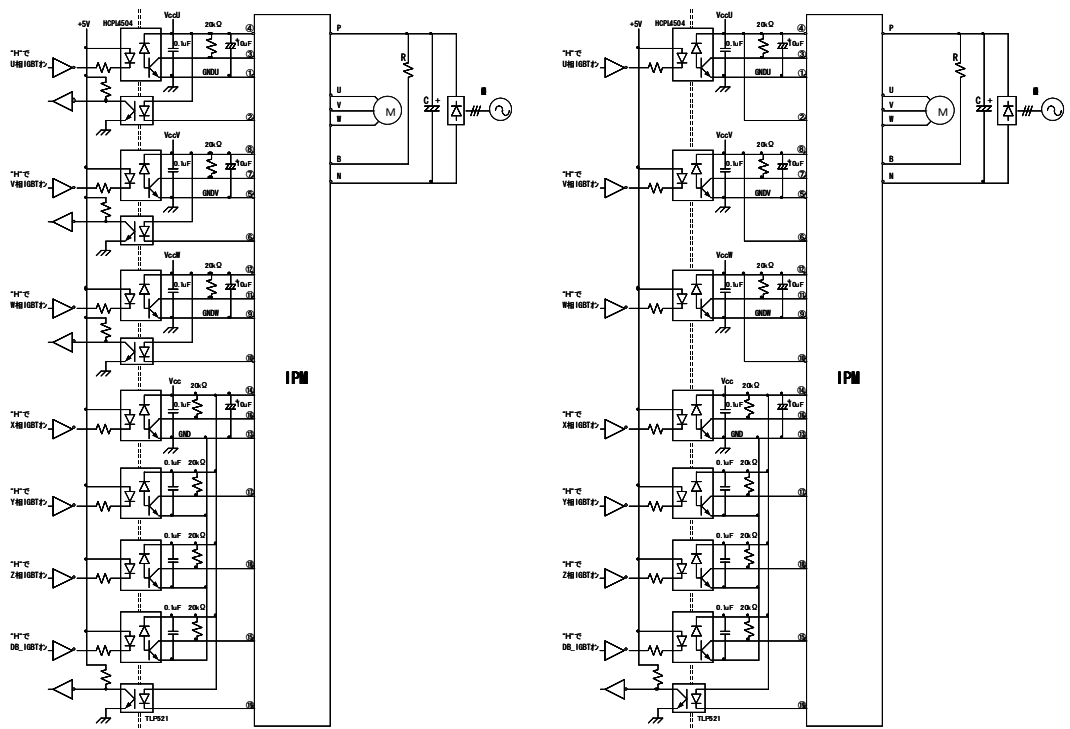
15. There is thermal interference between nearby power devices, because the Econo IPM is a compact package.

Therefore you measure the case temperature just under the IGBT chips that showed in report MT6M04545, and estimate the chip temperature.

Econo IPM はパッケージ小型化のため、パワー素子の熱干渉が考えられます。

その為、チップ温度推定は必ず MT6M04545 に示すチップ直下のケース温度を測定して行って下さい。

## 12. Example of applied circuit 応用回路例



(a) In case of use of High side alarm  
上アームアラーム使用の場合

(b) In case of no use of High side alarm  
上アームアラーム不使用の場合

## 13. Package and Marking 梱包仕様

Please see the MT6M4140 which is packing specification of IPM.  
IPM梱包仕様書 MT6M4140を御参照ください。

## 14. Cautions for storage and transportation 保管、運搬上の注意

- Store the modules at the normal temperature and humidity (5 to 35°C, 45 to 75%).  
常温常湿(5~35°C、45~75%)で保存して下さい。
- Avoid a sudden change in ambient temperature to prevent condensation on the module surfaces.  
モジュールの表面が結露しないよう、急激な温度変化を避けて下さい。
- Avoid places where corrosive gas generates or much dust exists.  
腐食性ガスの発生場所、粉塵の多い場所は避けて下さい。
- Store the module terminals under unprocessed conditions  
モジュールの端子は未加工の状態での保管すること。
- Avoid physical shock or falls during the transportation.  
運搬時に衝撃を与えたり落下させないで下さい。

## 15. Scope of application 適用範囲

This specification is applied to the IGBT-IPM (type: 7MBP75TEA120).  
本仕様書は、IGBT-IPM (型式:7MBP75TEA120)に適用する。

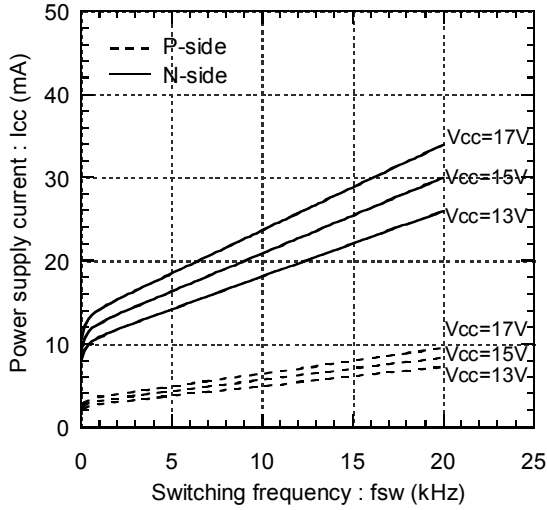
## 16. Based safety standards 準拠安全規格

UL1557

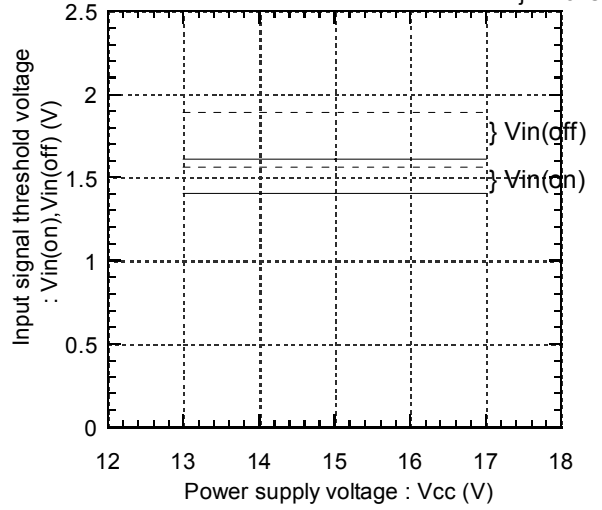
# 17. Characteristics

## 17-1. Control Circuit Characteristics (Representative)

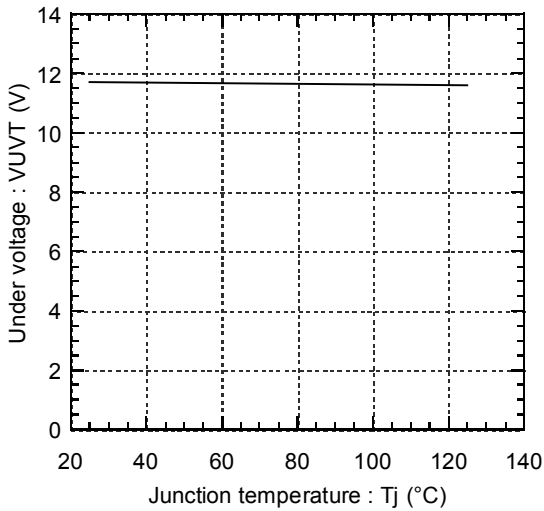
Power supply current vs. Switching frequency  
Tc=125°C (typ.)



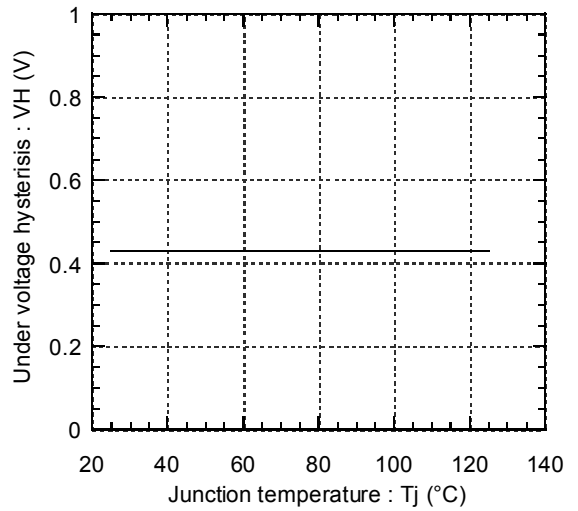
Input signal threshold voltage vs. Power supply voltage (typ.)  
Tj=25°C (solid line), Tj=125°C (dashed line)



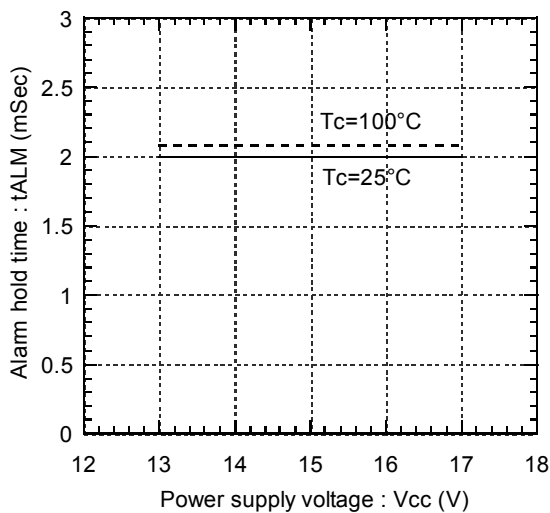
Under voltage vs. Junction temperature (typ.)



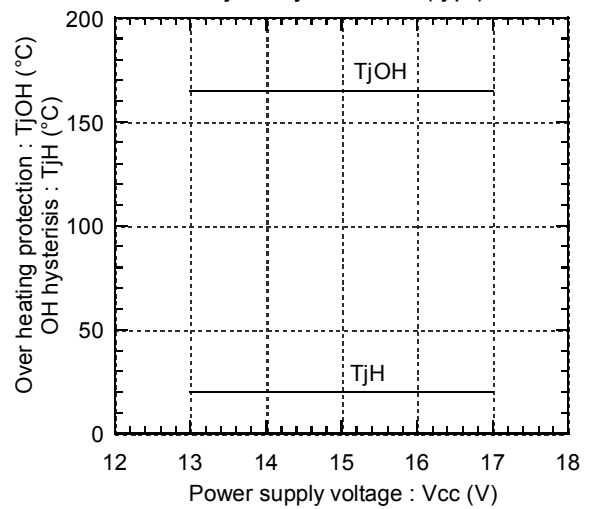
Under voltage hysteresis vs. Junction temperature (typ.)



Alarm hold time vs. Power supply voltage (typ.)



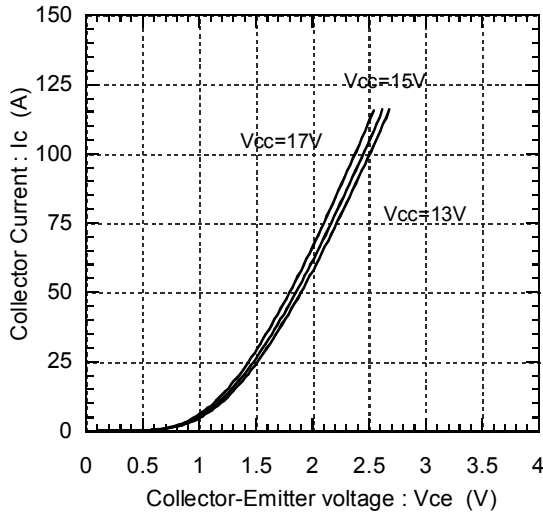
Over heating characteristics  
TjOH, TjH vs. Vcc (typ.)



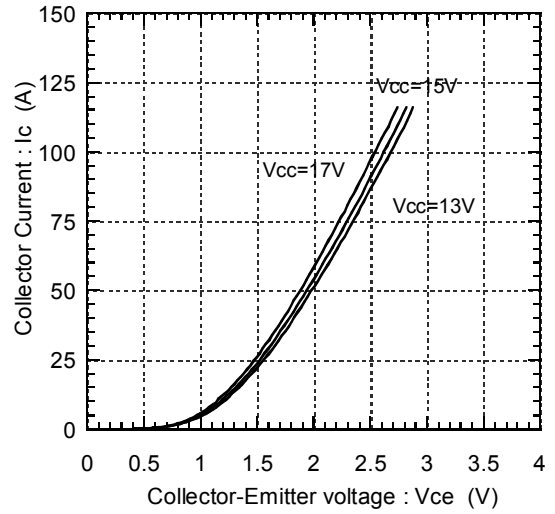
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## 17-2.Main Circuit Characteristics (Representative)

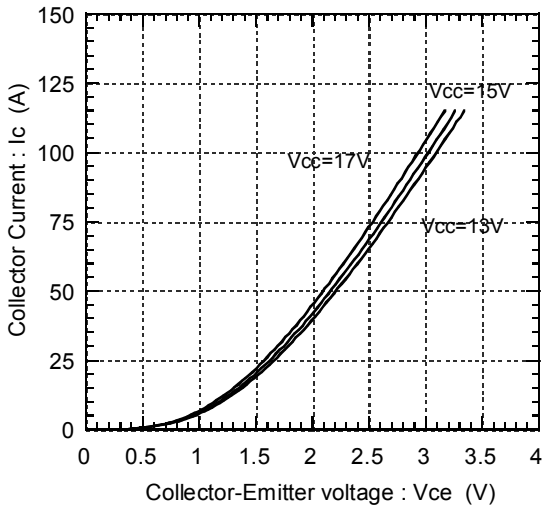
Collector current vs. Collector-Emittter voltage (typ.)  
T<sub>j</sub>=25°C(Chip)



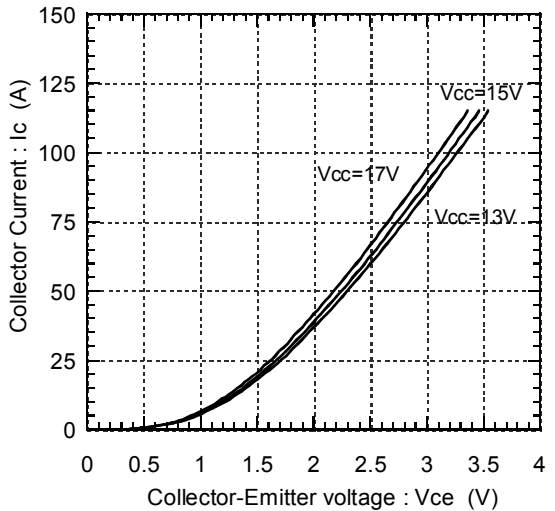
Collector current vs. Collector-Emittter voltage (typ.)  
T<sub>j</sub>=25°C(Terminal)



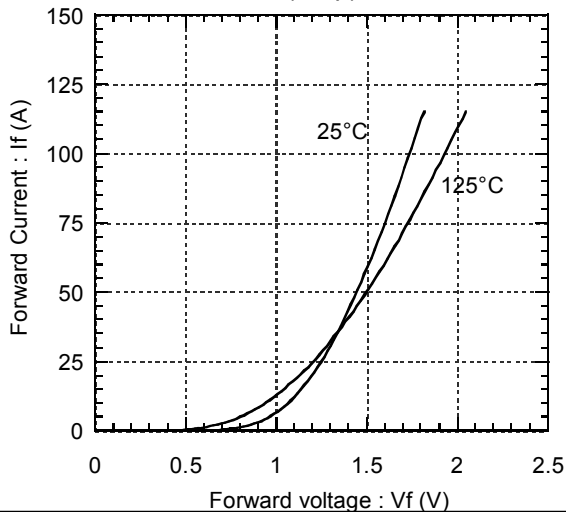
Collector current vs. Collector-Emittter voltage (typ.)  
T<sub>j</sub>=125°C(Chip)



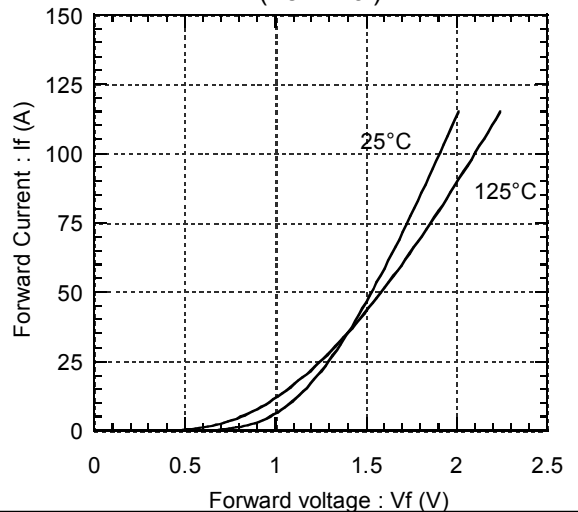
Collector current vs. Collector-Emittter voltage (typ.)  
T<sub>j</sub>=125°C(Terminal)



Forward current vs. Forward voltage (typ.)  
(Chip)



Forward current vs. Forward voltage (typ.)  
(Terminal)

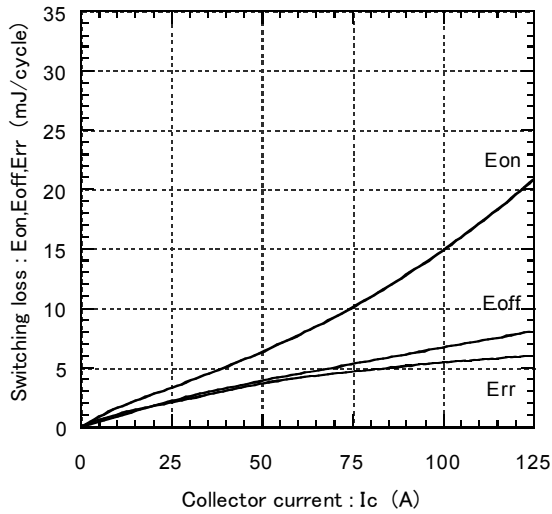


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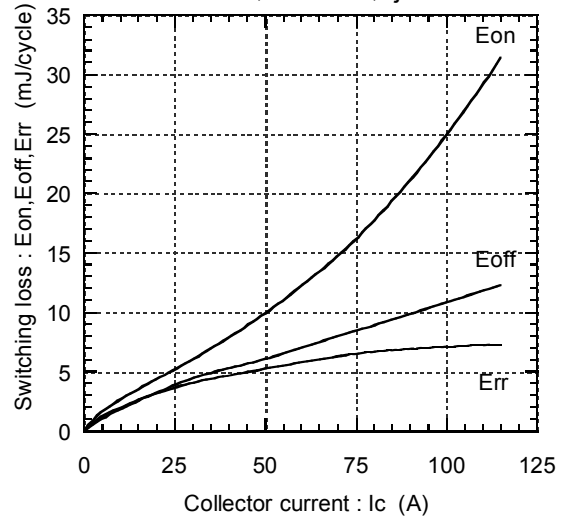


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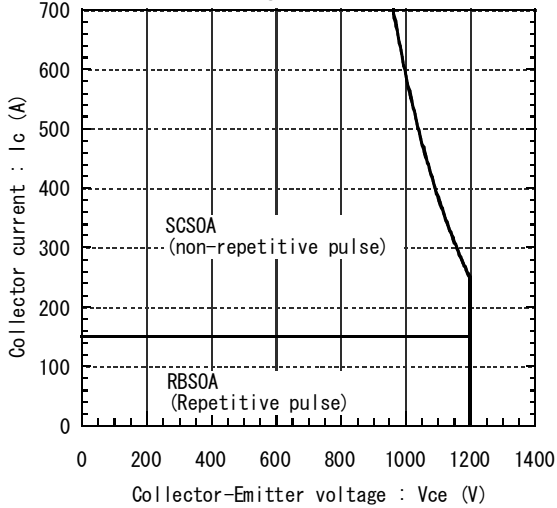
Switching Loss vs. Collector Current (typ.)  
 $E_{dc}=600V, V_{cc}=15V, T_j=25^\circ C$



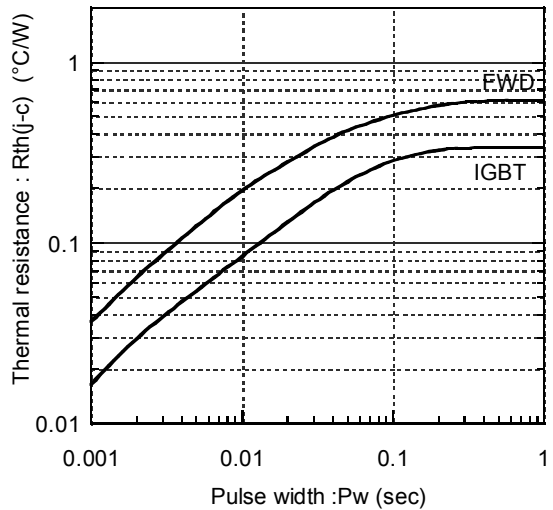
Switching Loss vs. Collector Current (typ.)  
 $E_{dc}=600V, V_{cc}=15V, T_j=125^\circ C$



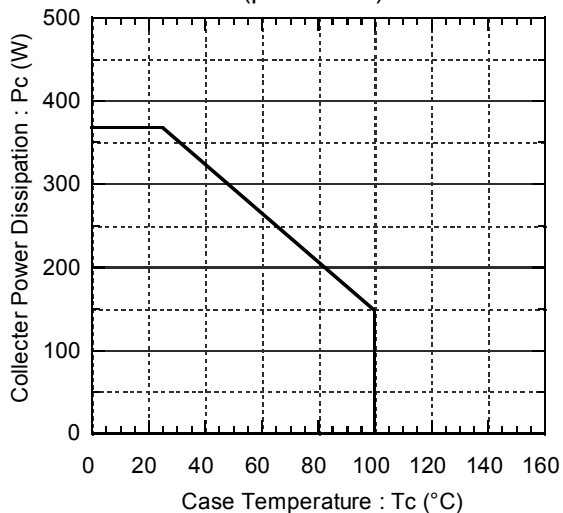
Reversed biased safe operating area  
 $V_{cc}=15V, T_j \le 125^\circ C$  (min.)



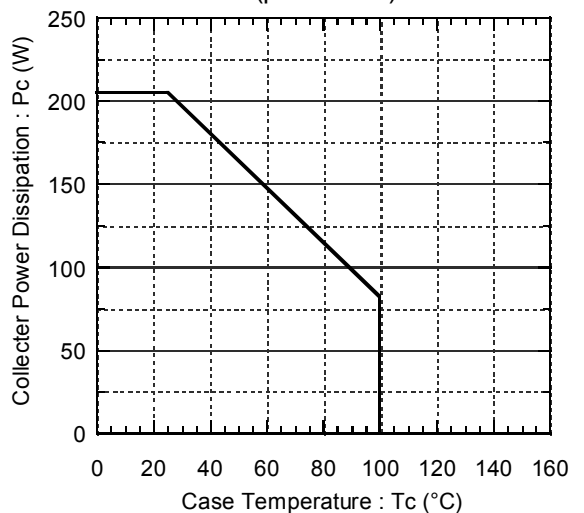
Transient thermal resistance (max.)



Power derating for IGBT (max.)  
 (per device)

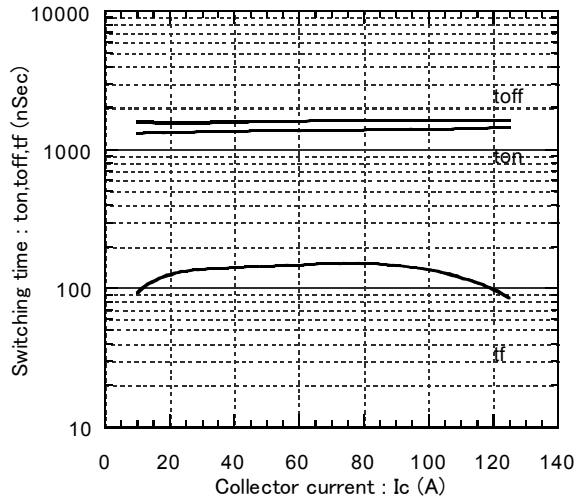


Power derating for FWD (max.)  
 (per device)

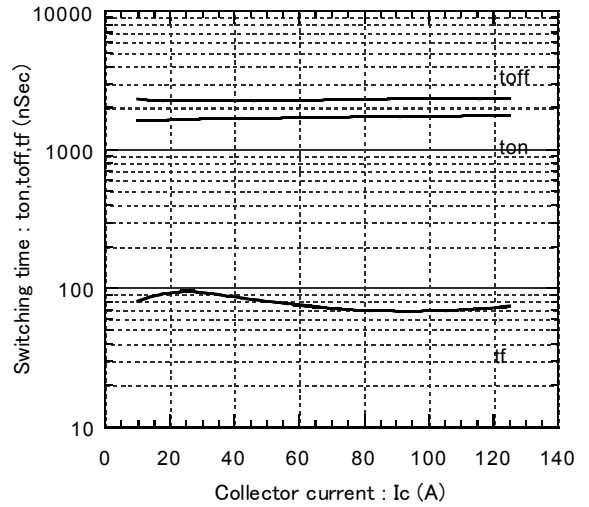


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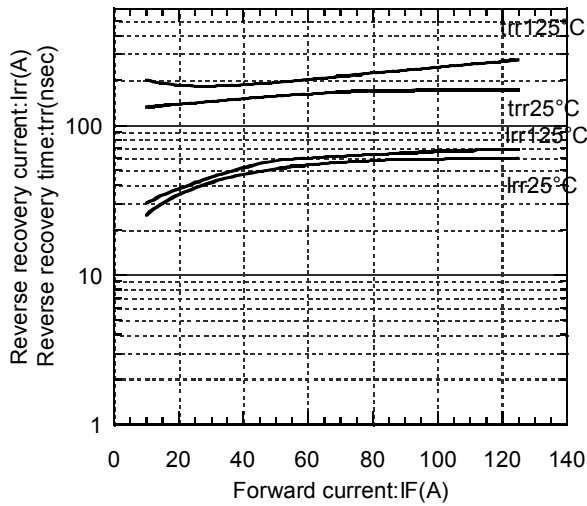
Switching time vs. Collector current (typ.)  
 $E_{dc}=600V, V_{cc}=15V, T_j=25^{\circ}C$



Switching time vs. Collector current (typ.)  
 $E_{dc}=600V, V_{cc}=15V, T_j=125^{\circ}C$

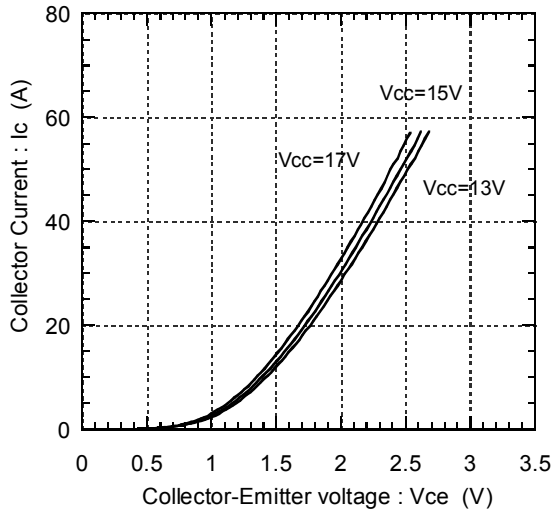


Reverse recovery characteristics (typ.)  
 $t_{rr}, I_{rr}$  vs.  $I_F$

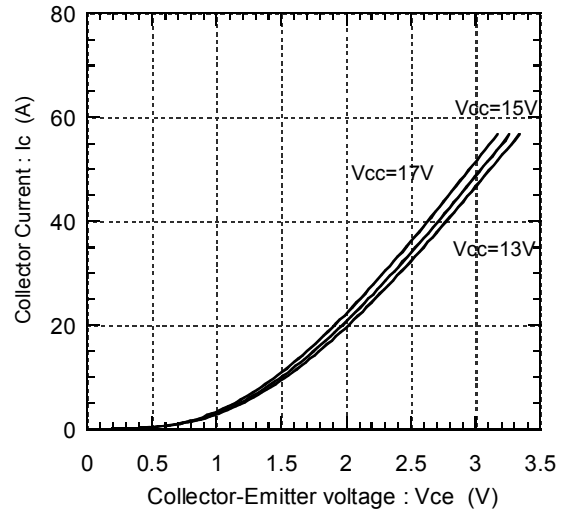


### 17-3.Dynamic Brake Characteristics (Representative)

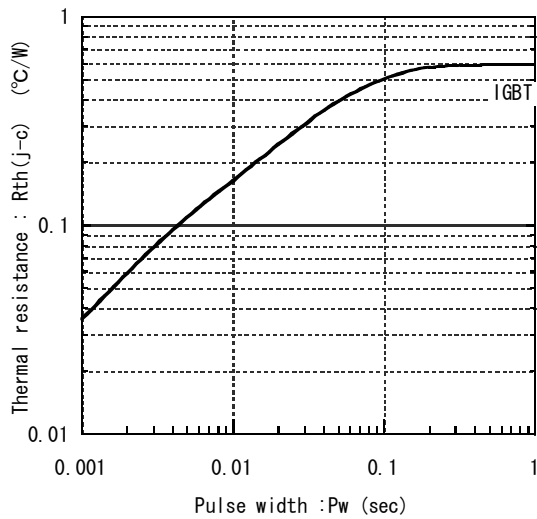
Collector current vs. Collector-Emittor voltage (typ.)  
 $T_j=25^{\circ}\text{C}$



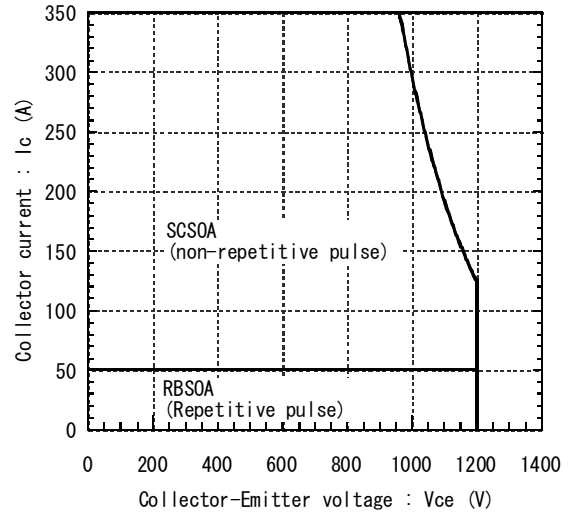
Collector current vs. Collector-Emittor voltage (typ.)  
 $T_j=125^{\circ}\text{C}$



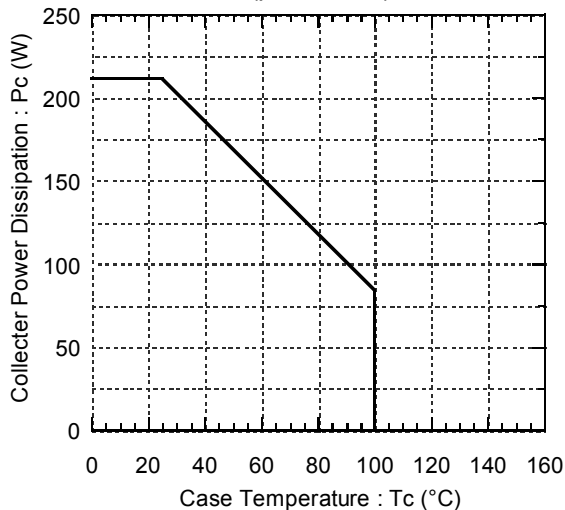
Transient thermal resistance (max.)



Reversed biased safe operating area  
 $V_{cc}=15\text{V}, T_j \leq 125^{\circ}\text{C}$  (min.)



Power derating for IGBT (max.)  
(per device)



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### 18. Reliability Test Items

Test categories	Test items	Test methods and conditions	Reference norms EIAJ ED-4701	Number of sample	Acceptance number
Mechanical Tests	1 Terminal strength 端子強度 (Pull test)	Pull force : 20 N (main terminal) 10 N (control terminal) Test time : 10 ±1 sec.	Test Method 401 Method I	5	(1 : 0)
	2 Mounting Strength 締付け強度	Screw torque : 2.5 ~ 3.5 N·m (M5) Test time : 10 ±1 sec.	Test Method 402 method II	5	(1 : 0)
	3 Vibration 振動	Range of frequency : 10~500 Hz Sweeping time : 15 min. Acceleration : 100 m/s <sup>2</sup> Sweeping direction : Each X,Y,Z axis Test time : 6 hr. (2hr./direction)	Test Method 403 Condition code B	5	(1 : 0)
	4 Shock 衝撃	Maximum acceleration : 5000 m/s <sup>2</sup> Pulse width : 1.0 ms Direction : Each X,Y,Z axis Test time : 3 times/direction	Test Method 404 Condition code B	5	(1 : 0)
	5 Solderability はんだ付け性	Solder temp. : 235 ±5 °C Immersion duration : 5.0 ±0.5 sec. Test time : 1 time Each terminal should be Immersed in solder within 1~1.5mm from the body.	Test Method 303 Condition code A	5	(1 : 0)
	6 Resistance to soldering heat はんだ耐熱性	Solder temp. : 260 ±5 °C Immersion time : 10 ±1sec. Test time : 1 time Each terminal should be Immersed in solder within 1~1.5mm from the body.	Test Method 302 Condition code A	5	(1 : 0)
Environment Tests	1 High temperature storage 高温保存	Storage temp. : 125 ±5 °C Test duration : 1000 hr.	Test Method 201	5	(1 : 0)
	2 Low temperature storage 低温保存	Storage temp. : -40 ±5 °C Test duration : 1000 hr.	Test Method 202	5	(1 : 0)
	3 Temperature humidity storage 高温高湿保存	Storage temp. : 85 ±2 °C Relative humidity : 85 ±5% Test duration : 1000hr.	Test Method 103 Test code C	5	(1 : 0)
	4 Unsaturated pressure cooker プレッシャークッカー	Test temp. : 120 ±2 °C Atmospheric pressure : 1.7×10 <sup>5</sup> Pa Test humidity : 85 ±5% Test duration : 96 hr.	Test Method 103 Test code E	5	(1 : 0)
	5 Temperature cycle 温度サイクル	Test temp. : Minimum storage temp. -40 ±5°C Maximum storage temp. 125 ±5°C Normal temp. 5 ~ 35°C Dwell time : Tmin ~ TN ~ Tmax ~ TN 1hr. 0.5hr. 1hr. 0.5hr. Number of cycles : 100 cycles	Test Method 105	5	(1 : 0)
	6 Thermal shock 熱衝撃	Test temp. : High temp. side 100 <sup>+0</sup> °C Low temp. side 0 <sup>-0</sup> °C Fluid used : Pure water (running water) Dipping time : 5 min. par each temp. Transfer time : 10 sec. Number of cycles : 10 cycles	Test Method 307 method I Condition code A	5	(1 : 0)

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Test categories	Test items	Test methods and conditions	Reference norms EIAJ ED-4701	Number of sample	Acceptance number
Endurance Tests	1 High temperature reverse bias 高温逆バイアス	Test temp. : $T_a = 125 \pm 5^\circ\text{C}$ ( $T_j \leq 150^\circ\text{C}$ ) Bias Voltage : $V_C = 0.8 \times V_{CES}$ Bias Method : Applied DC voltage to C-E $V_{CC} = 15\text{V}$ Test duration : 1000 hr.	Test Method 101	5	(1 : 0)
	2 Intermittent operating life (Power cycle) 断続動作	ON time : 2 sec. OFF time : 18 sec. Test temp. : $\Delta T_j = 100 \pm 5\text{deg}$ $T_j \leq 150^\circ\text{C}$ , $T_a = 25 \pm 5^\circ\text{C}$ Number of cycles : 15000 cycles	Test Method 106	5	(1 : 0)

### 19. Failure Criteria

Item	Characteristic	Symbol	Failure criteria		Unit	Note	
			Lower limit	Upper limit			
Electrical characteristic	Leakage current	ICES	-	USL $\times$ 2	mA		
	Saturation voltage	VCE(sat)	-	USL $\times$ 1.2	V		
	Forward voltage	VF	-	USL $\times$ 1.2	V		
	Thermal resistance	IGBT	Rth(j-c)	-	USL $\times$ 1.2	$^\circ\text{C}/\text{W}$	
		FWD	Rth(j-c)	-	USL $\times$ 1.2	$^\circ\text{C}/\text{W}$	
	Over Current Protection	I <sub>oc</sub>	LSL $\times$ 0.8	USL $\times$ 1.2	A		
	Alarm signal hold time	t <sub>ALM</sub>	LSL $\times$ 0.8	USL $\times$ 1.2	ms		
	Isolation voltage	Viso	Broken insulation		-		
Visual inspection	Visual inspection Peeling Plating and the others	-	The visual sample		-		

LSL : Lower specified limit.

USL : Upper specified limit.

Note : Each parameter measurement read-outs shall be made after stabilizing the components at room ambient for 2 hours minimum, 24 hours maximum after removal from the tests. And in case of the wetting tests, for example, moisture resistance tests, each component shall be made wipe or dry completely before the measurement.

## Warnings

1. This product shall be used within its absolute maximum rating (voltage, current, and temperature). This product may be broken in case of using beyond the ratings.

製品の絶対最大定格（電圧、電流、温度等）の範囲内で御使用下さい。絶対最大定格を超えて使用すると、素子が破壊する場合があります。

2. Connect adequate fuse or protector of circuit between three-phase line and this product to prevent the equipment from causing secondary destruction.

万一の不慮の事故で素子が破壊した場合を考慮し、商用電源と本製品の間適切な容量のヒューズ又はブレーカーを必ず付けて2次破壊を防いでください。

3. When studying the device at a normal turn-off action, make sure that working paths of the turn-off voltage and current are within the RBSOA specification. And ,when studying the device duty at a short-circuit current non-repetitive interruption, make sure that the paths are also within the SCSOA specification. In case of use of IGBT-IPM over these spcifications, it might be possible to be broken.

通常のターンオフ動作における素子責務の検討の際には、ターンオフ電圧・電流の動作軌跡がRBSOA仕様内にあることを確認して下さい。また、非繰返しの短絡電流遮断における素子責務の検討に際しては、SCSOA仕様内にある事を確認して下さい。

これらの仕様を越えて使用すると、素子が破壊する場合があります。

4. Use this product after realizing enough working on environment and considering of product's reliability life. This product may be broken before target life of the system in case of using beyond the product's reliability life.

製品の使用環境を十分に把握し、製品の信頼性寿命が満足できるか検討の上、本製品を適用して下さい。製品の信頼性寿命を超えて使用した場合、装置の目標寿命より前に素子が破壊する場合があります。

5. If the product had been used in the environment with acid, organic matter, and corrosive gas (For example : hydrogen sulfide, sulfurous acid gas), the product's performance and appearance can not be ensured easily.

酸・有機物・腐食性ガス（硫化水素、亜硫酸ガス等）を含む環境下で使用された場合、製品機能・外観などの保証は致しかねます。

6. The thermal stress generated from rise and fall of Tj restricts the product lifetime.

You should estimate the  $\Delta T_j$  from power losses and thermal resistance, and design the inverter lifetime within the number of cycles provided from the power cycle curve. (Technical Rep. No.: MT6M4057)

製品の寿命は、接合温度の上昇と下降によって起こる熱ストレスで決まります。損失と熱抵抗から $\Delta T_j$ を推定し、パワーサイクル寿命カーブで決まるサイクル数以下で、インバータの寿命を設計して下さい(技術資料№: MT6M4057)。

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7. Never add mechanical stress to deform the main or control terminal.

The deformed terminal may cause poor contact problem.

主端子及び制御端子に応力を与えて変形させないで下さい。端子の変形により、接触不良などを引き起こす場合があります。

8. If excessive static electricity is applied to the control terminals, the devices can be broken.

Implement some countermeasures against static electricity.

制御端子に過大な静電気が印加された場合、素子が破壊する場合があります。取り扱い時は静電気対策を実施して下さい。

### Caution

1. Fuji Electric is constantly making every endeavor to improve the product quality and reliability.

However, semiconductor products may rarely happen to fail or malfunction. To prevent accidents causing injury or death, damage to property like by fire, and other social damage resulted from a failure or malfunction of the Fuji Electric semiconductor products, take some measures to keep safety such as redundant design, spread-fire-preventive design, and malfunction-protective design.

富士電機は絶えず製品の品質と信頼性の向上に努めています。しかし、半導体製品は故障が発生したり、誤動作する場合があります。富士電機製半導体製品の故障または誤動作が、結果として人身事故・火災等による財産に対する損害や社会的な損害を起こさないように冗長設計・延焼防止設計・誤動作防止設計など安全確保のための手段を講じて下さい。

2. The application examples described in this specification only explain typical ones that used the Fuji Electric products. This specification never ensure to enforce the industrial property and other rights, nor license the enforcement rights.

本仕様書に記載してある応用例は、富士電機製品を使用した代表的な応用例を説明するものであり、本仕様書によって工業所有権、その他権利の実施に対する保障または実施権の許諾を行うものではありません。

3. The product described in this specification is not designed nor made for being applied to the equipment or systems used under life-threatening situations. When you consider applying the product of this specification to particular used, such as vehicle-mounted units, shipboard equipment, aerospace equipment, medical devices, atomic control systems and submarine relaying equipment or systems, please apply after confirmation of this product to be satisfied about system construction and required reliability.

本仕様書に記載された製品は、人命にかかわるような状況下で使用される機器あるいはシステムに用いられることを目的として設計・製造されたものではありません。本仕様書の製品を車両機器、船舶、航空宇宙、医療機器、原子力制御、海底中継機器あるいはシステムなど、特殊用途へのご利用をご検討の際は、システム構成及び要求品質に満足することをご確認の上、ご利用下さい。

If there is any unclear matter in this specification, please contact Fuji Electric Co., Ltd.

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